

208(a) : Development of the Equation of Motion for
Orbit in the Solar System.

The solar system orbit is the precessing ellipse.

$$r = \frac{d}{1 + \epsilon \cos(\alpha\theta)} \quad - (1)$$

and the new equation of motion is :

$$\frac{d\omega}{d\theta} = -F\omega \quad - (2)$$

where

$$F = \frac{d^2 f / d\theta^2}{df/d\theta} \quad - (3)$$

The equation (3) can be expressed as :

$$\frac{d\omega}{d\theta} \frac{df}{d\theta} + \omega \frac{d^2 f}{d\theta^2} = 0. \quad - (4)$$

For a circular orbit :

$$\frac{d\omega}{d\theta} = 0, \quad \omega = vr = \text{constant} \quad - (5)$$

$$\text{so} \quad \frac{d^2 f}{d\theta^2} = 0 \quad - (6)$$

where

$$f = r^2 \left(\frac{d\theta}{dr} \right)^2 \quad - (7)$$

$$\text{and} \quad \frac{d\theta}{dr} = \lim_{\delta r \rightarrow 0} \left(\frac{f(r + \delta r) - f(r)}{\delta r} \right) \quad - (8)$$

by definition.

2) For a circular orbit θ does not depend on r and θ does not change with r , i.e. θ and r are independent and

$$d\theta/dr = 0 \quad - (9)$$

so eq. (6) is true.

In the solar system:

$$e \ll 1 \quad - (10)$$

by observation.

So:

$$r = d(1 + e \cos \theta)^{-1} \\ \sim d(1 - e \cos \theta) \quad - (11)$$

It is also observed that:

$$e = 1 \quad - (12)$$

to an excellent approximation. So:

$$r \sim d(1 - e \cos \theta) \quad - (13)$$

Therefore:

$$\frac{dr}{d\theta} = -e d \sin \theta \quad - (14)$$

and

$$f = \left(\frac{r^2}{e d \sin \theta} \right)^2 \quad - (15) \\ = \left(\frac{1 - e \cos \theta}{e \sin \theta} \right)^2$$

3) Using eq. (10):

$$f \sim \left(\frac{1}{\epsilon \sin \theta} \right)^2 \quad - (16)$$

$$\begin{aligned} \text{So } \frac{df}{d\theta} &= \frac{1}{\epsilon^2} \frac{d}{d\theta} \left(\frac{1}{\sin^2 \theta} \right) \\ &= - \frac{1}{\epsilon^2} \frac{\cos \theta}{\sin^3 \theta} \end{aligned}$$

and:

$$\begin{aligned} \frac{d^2 f}{d\theta^2} &= - \frac{1}{\epsilon^2} \left(\frac{-\sin^4 \theta - 3 \sin^2 \theta \cos^2 \theta}{\sin^6 \theta} \right) \\ &= \frac{1}{\epsilon^2} \left(\frac{\sin^2 \theta + 3 \cos^2 \theta}{\sin^4 \theta} \right) \\ &= \frac{1}{\epsilon^2} \left(\frac{1 + 2 \cos^2 \theta}{\sin^4 \theta} \right) \quad - (17) \end{aligned}$$

$$\text{So } F = - \left(\frac{1 + 2 \cos^2 \theta}{\sin^4 \theta} \right) \frac{\sin^3 \theta}{\cos \theta}$$

$$\boxed{F = - \left(\frac{1 + 2 \cos^2 \theta}{\sin \theta \cos \theta} \right) \text{ for } \epsilon \ll 1} \quad - (18)$$

and

$$\frac{d\omega}{d\theta} = \left(\frac{1 + 2 \cos^2 \theta}{\sin \theta \cos \theta} \right) \omega \quad - (19)$$

4) Resolution is :

$$\int \frac{d\omega}{\omega} = \int \left(\frac{1 + 2 \cos^2 \theta}{\sin \theta \cos \theta} \right) d\theta = g(\theta) \quad - (20)$$

where $g(\theta)$ can be found by computer or integral tables. So

$$\omega = \omega_0 \exp(g(\theta)) \quad - (21)$$

However, in the limit (10), the orbital angular frequency is almost constant. Therefore eq. (21) is a small perturbation on the complete solution:

$$\Omega = \omega_1 + \omega \quad - (22)$$

where ω_1 is a constant such that:

$$\frac{d\Omega}{d\theta} = \frac{d\omega}{d\theta} \quad - (23)$$

So

$$\boxed{\Omega = \omega_1 + \omega_0 \exp(g(\theta))} \quad - (24)$$

Conclusion

Re theory predicts small perturbations in the orbit - given by the second term in eq. (24). These are not present in Newtonian orbits
