

215(7) : Classical Description of the Precession of the Perihelion.

Lagrangian dynamics gives the force equation:

$$\frac{d^2}{d\theta^2} \left(\frac{1}{r} \right) + \frac{1}{r} = - \frac{mr^2}{L} F(r) \quad - (1)$$

where the conserved total angular momentum is:

$$L = mr^2 \dot{\theta}. \quad - (2)$$

The orbit is:
$$r = \frac{d}{1 + \epsilon \cos(x\theta)} \quad - (3)$$

where

$2d = \text{Latus rectum}$

$\epsilon = \text{ellipticity}$

$x = \text{precession constant}$

From eq. (3):

$$\frac{dr}{d\theta} = \frac{x\epsilon}{d} r^2 \sin(x\theta) \quad - (4)$$

so:
$$\dot{r} = \frac{dr}{dt} = \frac{dr}{d\theta} \frac{d\theta}{dt} = \frac{x\epsilon L}{dm} \sin(x\theta) \quad - (5)$$

The orbital velocity is:

$$\underline{v} = \dot{r} \underline{e}_r + r \dot{\theta} \underline{e}_\theta \quad - (6)$$

so
$$v^2 = \dot{r}^2 + r^2 \dot{\theta}^2 \quad - (7)$$

It follows that:

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$$v^2 = \left(\frac{x L \epsilon}{d m} \right)^2 \sin^2(x\theta) + \left(\frac{L}{m r} \right)^2 - (8)$$

This is already a valid classical description of the precession of the perihelion. This equation can be tested experimentally. The observables are:

v = linear velocity of the planet

$\omega = d\theta/dt$ = angular velocity of the planet

m = mass of the planet

$2d$ = major radius of the orbit

ϵ = ellipticity of the orbit

x = precession constant

r = distance from sun to planet.

Testing eq. (8) should be straightforward with contemporary astronomy.

Eq. (8) results in a small correction to Kepler's equation for v as follows.

Note that:

$$1 + \epsilon \cos(x\theta) = \frac{d}{r} - (9)$$

so

$$\cos(x\theta) = \frac{1}{\epsilon} \left(\frac{d}{r} - 1 \right) - (10)$$

Now use:

$$\sin^2(x\theta) + \cos^2(x\theta) = 1 - (11)$$

So:

$$\sin^2(\alpha\theta) = 1 - \frac{1}{\epsilon^2} \left(\frac{d}{r} - 1 \right)^2 \quad - (12)$$

Therefore:

$$\begin{aligned} v^2 &= \left(\frac{L}{m} \right)^2 \left[\left(\frac{x\epsilon}{d} \right)^2 \left(1 - \frac{1}{\epsilon^2} \left(\frac{d}{r} - 1 \right)^2 \right) + \frac{1}{r^2} \right] \quad - (13) \\ &= \left(\frac{L}{m} \right)^2 \left[\frac{x^2 \epsilon^2}{d^2} - \frac{x^2}{d^2} \left(\frac{d}{r} - 1 \right)^2 + \frac{1}{r^2} \right] \\ &= \left(\frac{L}{m} \right)^2 \left[\frac{x^2 \epsilon^2}{d^2} - \frac{x^2}{d^2} \left(\frac{d-r}{r} \right)^2 + \frac{1}{r^2} \right] \\ &= \left(\frac{L}{m} \right)^2 \left[\frac{x^2 \epsilon^2}{d^2} + \frac{1}{r^2} \left(1 - \frac{x^2}{d^2} (d-r)^2 \right) \right] \\ &= \left(\frac{L}{m} \right)^2 \left[\frac{x^2 \epsilon^2}{d^2} + \frac{1}{r^2} \left(\frac{d^2 - x^2 (d-r)^2}{d^2} \right) \right] \\ &= \left(\frac{L}{m} \right)^2 \left[\frac{x^2 \epsilon^2}{d^2} + \frac{1}{r^2} \left(\frac{d^2 - x^2 (d^2 - 2dr + r^2)}{d^2} \right) \right] \\ &= \left(\frac{L}{m} \right)^2 \left[\frac{x^2 \epsilon^2}{d^2} + \frac{1}{r^2} \left(1 - x^2 \right) + \frac{2x^2}{dr} - \left(\frac{x}{d} \right)^2 \right] \\ &= \left(\frac{L}{md} \right)^2 \left[x^2 (\epsilon^2 - 1) + \frac{2x^2 d}{r} + \frac{d^2}{r^2} (1 - x^2) \right] \end{aligned}$$

Therefore:

$$* \quad v^2 = \left(\frac{L}{md} \right)^2 \left[\frac{2x^2 d}{r} - x^2 (1 - \epsilon^2) + \frac{d^2}{r^2} (1 - x^2) \right] \quad - (14)$$

4) The Newtonian result is given by:

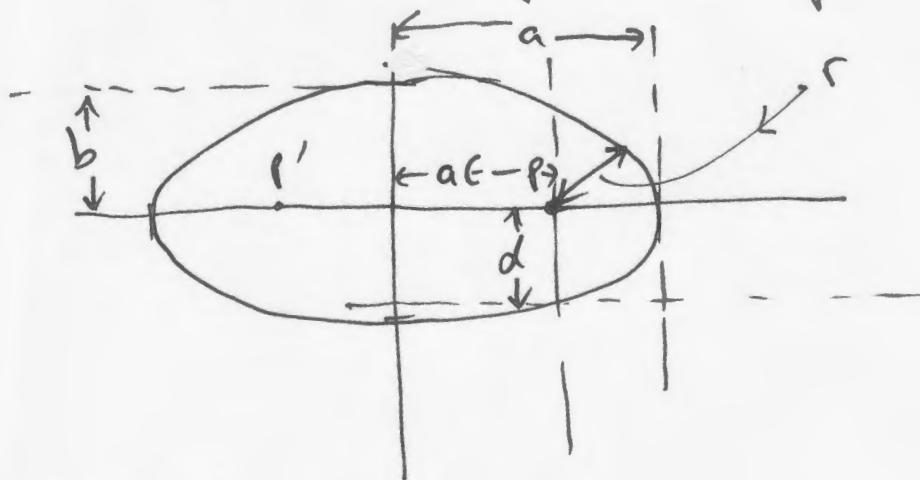
$$x = 1. \quad - (15)$$

$$\text{so } v_N^2 = \left(\frac{L}{md}\right)^2 \left[\frac{2d}{r} - (1 - e^2) \right] \quad - (16)$$

which is eq. (7) of note 215(6) QED.

Comparing eqs. (14) and (16) it is seen that the precession of the perihelion produces an additional term in $1/r^2$ and modifies the other two terms by x^2 .

The ellipse is defined as follows.



The semi major axis is:

$$a = \frac{d}{1 - e^2} \quad - (17)$$

and the semi minor axis is:

$$b^2 = \frac{d^2}{1 - e^2} \quad - (18)$$

As the ellipse precesses according to eq. (3) it does not change its shape, so eqs. (17) and (18) are also true for a precessing ellipse.

So eq. (14) is:

$$v^2 = \left(\frac{L}{md}\right)^2 \left[\frac{2x^2 d}{r} \right] - \frac{x^2}{b^2} \left(\frac{L}{m}\right)^2 + \left(\frac{L}{m}\right)^2 \left(\frac{1-x^2}{r^2} \right)$$

$$v^2 = \left(\frac{2x^2 L^2}{m^2 d} \right) \frac{1}{r} + \left(\frac{L}{m}\right)^2 \left(\frac{1-x^2}{r^2} - \frac{x^2}{b^2} \right)$$

i.e.
$$v^2 = \left(\frac{L}{m}\right)^2 \left[\frac{2x^2}{d} \cdot \frac{1}{r} + \frac{1-x^2}{r^2} - \frac{x^2}{b^2} \right]$$

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Finally d can be eliminated using:

$$d = a(1-e^2) \quad \text{--- (20)}$$

so
$$v^2 = \left(\frac{L}{m}\right)^2 \left[\frac{2x^2}{(1-e^2)a} \cdot \frac{1}{r} + \frac{1-x^2}{r^2} - \frac{x^2}{b^2} \right]$$

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which is the best suited for astronomy.

To test this by astronomy, a and b

b) are measured using distances of closest approach:

$$r_{\min} = a(1 - e) = \frac{d}{1 + e} \quad - (22)$$

and furthest away:

$$r_{\max} = a(1 + e) = \frac{d}{1 - e} \quad - (23)$$

Resolving simultaneous equations for a and e or d and e . What are actually observed are r_{\min} and r_{\max} . The precession constant α can be found by the precession of the perihelion.

Finally the quantity L/m has to be found. It is given by:

$$\frac{L}{m} = r^2 \omega \quad - (24)$$

The distance r and the angular velocity ω of the planet have to be measured. The linear velocity v of the planet has to be measured.

The precession of the perihelion of a planet in the solar system is due to Lagrangian dynamics, not to general relativity.