

219(11) : The Four Particle Problem

The Lagrangian in this case is:

$$\begin{aligned} L = & \frac{1}{2} (m_1 |\dot{\underline{r}}_1|^2 + m_2 |\dot{\underline{r}}_2|^2 + m_3 |\dot{\underline{r}}_3|^2 + m_4 |\dot{\underline{r}}_4|^2) \\ & - \frac{m_1 m_2 G}{|\underline{r}_1 - \underline{r}_2|} - \frac{m_1 m_3 G}{|\underline{r}_1 - \underline{r}_3|} - \frac{m_2 m_3 G}{|\underline{r}_2 - \underline{r}_3|} \\ & - \frac{m_1 m_4 G}{|\underline{r}_1 - \underline{r}_4|} - \frac{m_2 m_4 G}{|\underline{r}_2 - \underline{r}_4|} - \frac{m_3 m_4 G}{|\underline{r}_3 - \underline{r}_4|} \end{aligned} \quad - (1)$$

The Lagrangian is written as:

$$L = \frac{1}{3} (L_1 + L_2 + L_3 + L_4 + L_5 + L_6) \quad - (2)$$

where:

$$L_1 = \frac{1}{2} (m_1 |\dot{\underline{r}}_1|^2 + m_2 |\dot{\underline{r}}_2|^2) - \frac{3 m_1 m_2 G}{|\underline{r}_1 - \underline{r}_2|} \quad - (3)$$

$$L_2 = \frac{1}{2} (m_1 |\dot{\underline{r}}_1|^2 + m_3 |\dot{\underline{r}}_3|^2) - \frac{3 m_1 m_3 G}{|\underline{r}_1 - \underline{r}_3|} \quad - (4)$$

$$L_3 = \frac{1}{2} (m_2 |\dot{\underline{r}}_2|^2 + m_3 |\dot{\underline{r}}_3|^2) - \frac{3 m_2 m_3 G}{|\underline{r}_2 - \underline{r}_3|} \quad - (5)$$

$$L_4 = \frac{1}{2} (m_1 |\dot{\underline{r}}_1|^2 + m_4 |\dot{\underline{r}}_4|^2) - \frac{3 m_1 m_4 G}{|\underline{r}_1 - \underline{r}_4|} \quad - (6)$$

$$L_5 = \frac{1}{2} (m_2 |\dot{\underline{r}}_2|^2 + m_4 |\dot{\underline{r}}_4|^2) - \frac{3 m_2 m_4 G}{|\underline{r}_2 - \underline{r}_4|} \quad - (7)$$

$$L_6 = \frac{1}{2} (m_3 |\dot{\underline{r}}_3|^2 + m_4 |\dot{\underline{r}}_4|^2) - \frac{3 m_3 m_4 G}{|\underline{r}_3 - \underline{r}_4|} \quad - (8)$$

d) Now we:

$$m_1 \underline{r}_1 + m_2 \underline{r}_2 = \underline{0} \quad - (9)$$

$$m_2 \underline{r}_2 + m_3 \underline{r}_3 = \underline{0} \quad - (10)$$

$$m_1 \underline{r}_1 + m_3 \underline{r}_3 = \underline{0} \quad - (11)$$

$$m_1 \underline{r}_1 + m_4 \underline{r}_4 = \underline{0} \quad - (12)$$

$$m_2 \underline{r}_2 + m_4 \underline{r}_4 = \underline{0} \quad - (13)$$

$$m_3 \underline{r}_3 + m_4 \underline{r}_4 = \underline{0} \quad - (14)$$

which calculate the centres of mass of each interacting pairs of particles. Next define:

$$\mu_1 = \frac{m_1 m_2}{m_1 + m_2}, \mu_2 = \frac{m_1 m_3}{m_1 + m_3}, \mu_3 = \frac{m_2 m_3}{m_2 + m_3},$$

$$\mu_4 = \frac{m_1 m_4}{m_1 + m_4}, \mu_5 = \frac{m_2 m_4}{m_2 + m_4}, \mu_6 = \frac{m_3 m_4}{m_3 + m_4}. \quad - (15)$$

Also define:

$$k_1 = 3m_1 m_2 G, k_2 = 3m_1 m_3 G, k_3 = 3m_2 m_3 G,$$

$$k_4 = 3m_1 m_4 G, k_5 = 3m_2 m_4 G, k_6 = 3m_3 m_4 G. \quad - (16)$$

As is note 219(10) the six Lagrangians (3) to (8) reduce to the general format:

$$L = \frac{1}{2} \mu |\dot{\underline{r}}|^2 - U(r) \quad - (17)$$

The Euler-Lagrange equations are:

$$\frac{\partial \mathcal{L}}{\partial r} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{r}} \quad - (18)$$

and

$$\frac{\partial \mathcal{L}}{\partial \theta} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\theta}} \quad - (19)$$

i.e

$$\frac{d^2}{d\theta^2} \left(\frac{1}{r} \right) + \frac{1}{r} = - \frac{\mu r^2}{L^2} F(r) \quad - (20)$$

where

$$F(r) = - \mathcal{U}(r) / dr. \quad - (21)$$

Therefore there are six orbits for each pair of particles:

$$r_i = \frac{d_i}{1 + \epsilon_i \cos \theta}, \quad i=1, \dots, 6 \quad - (22)$$

where

$$d_i = \frac{L_i^2}{\mu_i k_i}, \quad i=1, \dots, 6 \quad - (23)$$

$$\epsilon_i = \left(1 + \frac{2E_i L_i^2}{\mu_i k_i^2} \right)^{1/2}, \quad i=1, \dots, 6 \quad - (24)$$

with:

$$L_i = \mu_i r_i^2 \dot{\theta}, \quad - (25)$$

$$i = 1, \dots, 6$$

The orbits are constrained by the fact that θ has no index (no subscript i), so:

4)

$$\cos\theta = \frac{1}{\epsilon_i} \left(\frac{d_i}{r_i} - \frac{1}{r_i} \right), \quad - (26)$$

$$i = 1, \dots, b,$$

giving:

$$r_{i+1} = d_{i+1} \left(1 - \frac{\epsilon_{i+1}}{\epsilon_i} \left(\frac{d_i - r_i}{r_i} \right) \right) \quad - (27)$$

$$i = 1, \dots, b.$$

Therefore:

$$r_{i+2} = d_{i+2} \left(1 - \frac{\epsilon_{i+2}}{\epsilon_{i+1}} \left(\frac{d_{i+1} - r_{i+1}}{r_{i+1}} \right) \right) \quad - (28)$$

with r_{i+1} given by eq. (27).

This procedure can be extended to N ^{pair} particles:

$$i = 1, \dots, N.$$

Example: 3 particles.

In this case: $i = 1, 2, 3. \quad - (29)$

So:

$$r_3 = d_3 \left(1 - \frac{\epsilon_3}{\epsilon_2} \left(\frac{d_2 - r_2}{r_2} \right) \right), \quad - (30)$$

where:

$$5) \quad r_2 = d_2 \left(1 - \frac{\epsilon_2}{\epsilon_1} \left(\frac{d_1 - r_1}{r_1} \right) \right) \quad - (31)$$

and
$$r_1 = \frac{d_1}{1 + \epsilon_1 \cos \theta} \quad - (32)$$

In addition:

$$r_2 = \frac{d_2}{1 + \epsilon_2 \cos \theta} \quad - (33)$$

$$r_3 = \frac{d_3}{1 + \epsilon_3 \cos \theta} \quad - (34)$$

$$\frac{1}{\epsilon_1} \left(\frac{d_1}{r_1} - 1 \right) = \frac{1}{\epsilon_2} \left(\frac{d_2}{r_2} - 1 \right) \quad - (35)$$

$$\frac{1}{\epsilon_1} \left(\frac{d_1}{r_1} - 1 \right) = \frac{1}{\epsilon_3} \left(\frac{d_3}{r_3} - 1 \right) \quad - (36)$$

$$\frac{1}{\epsilon_2} \left(\frac{d_2}{r_2} - 1 \right) = \frac{1}{\epsilon_3} \left(\frac{d_3}{r_3} - 1 \right) \quad - (37)$$

Eqs. (32) to (37) are six equations in nine unknowns.
To find three more equations we:

$$d_i = \frac{L_i}{\mu_i k_i} = \frac{\mu_i r_i^2}{k_i} \quad i = 1, 2, 3 \quad - (38)$$

Therefore:

6)

$$\frac{d_1}{d_2} = \frac{\mu_1 r_1^2}{k_1} \frac{k_2}{\mu_2 r_2} = \left(\frac{\mu_1}{\mu_2} \right) \left(\frac{k_2}{k_1} \right) \left(\frac{r_1}{r_2} \right)^2 \quad - (39)$$

Here:

$$\mu_1 = \frac{m_1 m_2}{m_1 + m_2}, \quad \mu_2 = \frac{m_1 m_3}{m_1 + m_3} \quad - (40)$$

$$k_1 = 3 m_1 m_2 G, \quad k_2 = 3 m_1 m_3 G.$$

$$\text{So } \frac{d_1}{d_2} = \left(\frac{m_1 + m_3}{m_1 + m_2} \right) \left(\frac{r_1}{r_2} \right)^2 \quad - (41)$$

$$\frac{d_1}{d_3} = \left(\frac{m_2 + m_3}{m_1 + m_2} \right) \left(\frac{r_1}{r_3} \right)^2 \quad - (42)$$

$$\frac{d_2}{d_3} = \left(\frac{m_2 + m_3}{m_1 + m_3} \right) \left(\frac{r_2}{r_3} \right)^2 \quad - (43)$$

This gives a set of nine equations, (32), (33), (34), (35), (36), (37), (41), (42) and (43) i.e. nine unknowns: $r_1, r_2, r_3, d_1, d_2, d_3, t_1, t_2, t_3$.

Conclusion

The problem is soluble analytically.