

5.10(3): Initial Condition

In general the field equations show that:

$$\frac{\ddot{x}}{\ddot{y}} = \frac{\kappa_x}{\kappa_y} \quad - (1)$$

many force equations. Therefore eq. (1) can be used as an initial condition:

$$\frac{\ddot{x}(0)}{\ddot{y}(0)} = \frac{\kappa_x(0)}{\kappa_y(0)} \quad - (2)$$

full solution of the various force equations. The orbit will depend on the initial condition, and therefore will depend on $\kappa_x(0)$ and $\kappa_y(0)$. Having chosen the initial $\ddot{x}(0)$ and $\ddot{y}(0)$, the orbit can be computed.

For Newtonian dynamics and retrograde precession:

$$\frac{\ddot{x}(0)}{\ddot{y}(0)} = \frac{\dot{x}(0)}{\dot{y}(0)} = \frac{\kappa_x(0)}{\kappa_y(0)} \quad - (3)$$

or forward precession:

$$\begin{aligned} \frac{\ddot{x}(0)}{\ddot{y}(0)} &= \left(\frac{\dot{x}(0)\dot{y}(0)\dot{y}(0) + x(0)\dot{x}^2(0)}{c^2} - x(0) \right) \left(\frac{\dot{x}(0)\dot{y}(0)x(0) + y(0)\dot{y}^2(0)}{c^2} - y(0) \right)^{-1} \\ &= \frac{\kappa_x(0)}{\kappa_y(0)} \quad - (4) \end{aligned}$$

For example, if static ellipse is:

$$r = \frac{a}{1 + e \cos \phi} \quad - (5)$$

and at the perihelion:

$$\phi = 2\pi n, n=0, 1, 2, \dots \quad - (6)$$

so at perihelion:

$$r = (x^2 + y^2)^{1/2} = \frac{d}{1+e} \quad - (7)$$

here the half right distance d and eccentricity e are known from astronomy. If the perihelion is chosen as the initial condition:

$$r(0) = (x(0)^2 + y(0)^2)^{1/2} = \frac{d}{1+e} \quad - (8)$$

$$\text{so } \left(x(0)^2 + \left(\frac{\kappa_y(0)}{\kappa_x(0)} x(0) \right)^2 \right)^{1/2} = \frac{d}{1+e} \quad - (9)$$

$$\text{so } x(0) = \left(\frac{d}{1+e} \right) \left(1 + \left(\frac{\kappa_y(0)}{\kappa_x(0)} \right)^2 \right)^{-1/2} \quad - (10)$$

At the initial position the equation of the ellipse is:

$$\frac{x(0)^2}{a^2} + \frac{y(0)^2}{b^2} = 1 \quad - (11)$$

$$\text{so } x^2(0) \left(\frac{1}{a^2} + \frac{1}{b^2} \left(\frac{\kappa_y(0)}{\kappa_x(0)} \right)^2 \right) = 1 \quad - (12)$$

$$\text{and } x(0) = \left(\frac{1}{a^2} + \frac{1}{b^2} \left(\frac{\kappa_y(0)}{\kappa_x(0)} \right)^2 \right)^{-1/2} \quad - (13)$$

From eq. (10) and (13) it is clear that $x(0)$

~~$$\frac{1}{a^2} + \frac{1}{b^2} \left(\frac{\kappa_y(0)}{\kappa_x(0)} \right)^2 = \frac{1}{a^2} + \frac{1}{b^2} \left(\frac{\kappa_y(0)}{\kappa_x(0)} \right)^2 \quad - (14)$$~~

depends on $K_y(0)$ and $K_x(0)$.

In general for a Newtonian orbit:

$$\frac{\ddot{x}}{\ddot{y}} = \frac{x}{y} = \frac{K_x}{K_y} \quad - (14)$$

$$\ddot{x} = -mG \frac{x}{(x^2 + y^2)^{3/2}} \quad - (15)$$

$$\ddot{y} = -mG \frac{y}{(x^2 + y^2)^{3/2}} \quad - (16)$$

From eq. (14): $x K_y - y K_x = 0 \quad - (17)$

and $\ddot{x} K_y - \ddot{y} K_x = 0 \quad - (18)$

therefore $\left(\frac{K_x}{K_y}\right) \ddot{y} = -mG \frac{x}{(x^2 + y^2)^{3/2}} \quad - (19)$

and $\left(\frac{K_y}{K_x}\right) \ddot{x} = -mG \frac{y}{(x^2 + y^2)^{3/2}} \quad - (20)$

For Jovian precession:

$$\ddot{x} = -\frac{mG}{r^3} \frac{x}{(x^2 + y^2)^{3/2}} \quad - (21)$$

$$\ddot{y} = -\frac{mG}{r^3} \frac{y}{(x^2 + y^2)^{3/2}} \quad - (22)$$

and :

$$4) \frac{\ddot{x}(\text{precessing})}{\ddot{x}(\text{static})} = \gamma^3 = \left(1 - \frac{\dot{x}^2 + \dot{y}^2}{c^2}\right)^{-3/2} - (23)$$

$$= \frac{\ddot{y}(\text{precessing})}{\ddot{y}(\text{static})} - (24)$$

so to maximise the difference between the precessing and static orbits:

$$v^2 = \frac{\dot{x}^2 + \dot{y}^2}{c^2} - (25)$$

must be maximised.

Retrograde precession again defies eq. (14), but the individual spirals are different. The problem is best solved by regarding the general result (14) as an initial condition:

$$\frac{\ddot{x}(0)}{\ddot{y}(0)} = \frac{x(0)}{y(0)} = \frac{\kappa_x(0)}{\kappa_y(0)} - (26)$$

Then solving eqs. (15) and (16) or (21) and (22) simultaneously. A similar procedure should be used for forward precession, in which case:

$$\frac{\ddot{x}(0)}{\ddot{y}(0)} = \frac{\kappa_x(0)}{\kappa_y(0)} - (27)$$

but

$$\frac{\ddot{x}(0)}{\ddot{y}(0)} \neq \frac{x(0)}{y(0)} - (28)$$